

Uniform accuracy from geometric high-order averaging

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Outline

1 Highly-oscillatory problems

- Behaviour of highly-oscillatory problems
- Geometric properties of averaging

2 High-order averaging

- The averaging ansatz and normal forms
- Well-posedness of the averaged model
- The quasi-periodic case

3 Numerical experiments

- Computing the change of variable and the pullback
- Validation on the Hénon-Heiles model

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A more general model

We are concerned with models of the form

$$\partial_t y^\varepsilon = \frac{1}{\varepsilon} A y^\varepsilon + f(y^\varepsilon), \quad y^\varepsilon(0) = y_0 \in \mathbb{R}^d$$

where $\tau \mapsto e^{\tau A}$ is (quasi-)periodic.

Examples

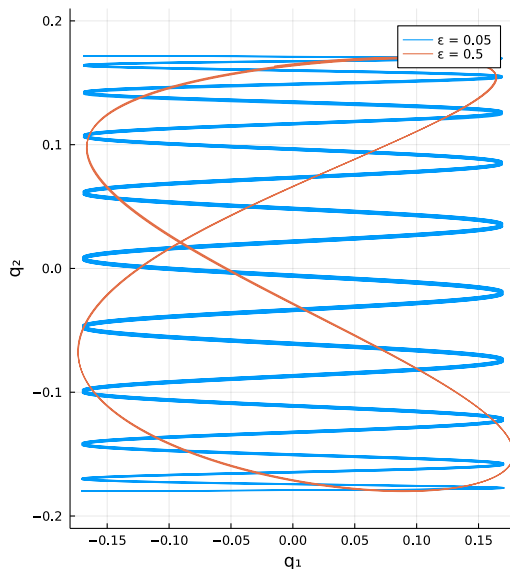
- Discretised non-linear Schrödinger

$$i\partial_t \psi^\varepsilon = -\frac{1}{\varepsilon} \Delta \psi^\varepsilon + |\psi^\varepsilon|^2 \psi^\varepsilon$$

- Particle methods for Vlasov equation with stiff magnetic field

$$\partial_t f^\varepsilon + v \cdot \nabla_x f^\varepsilon + \left(E + \frac{1}{\varepsilon} v \times B \right) \cdot \nabla_v f^\varepsilon = 0$$

Introducing the stiff Hénon-Heiles model



$$\begin{cases} \dot{p}_1 = -\frac{1}{\varepsilon}q_1 - 2q_1q_2 \\ \dot{p}_2 = -q_2 - q_1^2 + q_2^2 \\ \dot{q}_1 = \frac{1}{\varepsilon}p_1 \\ \dot{q}_2 = p_2 \end{cases}$$

Figure: Trajectories of the Hénon-Heiles model with initial data $(p_1, p_2, q_1, q_2) = (0.12, 0.12, 0.12, 0.12)$ for $t \in [0, 20]$.

Appropriate numerical methods

$$\partial_t y^\varepsilon = \frac{1}{\varepsilon} A y^\varepsilon + f(y^\varepsilon), \quad y^\varepsilon(0) = y_0 \in X$$

Exponential integrators based on the integral form

$$y^\varepsilon(t) = e^{tA/\varepsilon} y_0 + \int_0^t e^{(t-s)A} f(y^\varepsilon(s)) ds,$$

Lawson methods RK scheme on the filtered problem

$$u^\varepsilon(t) = e^{-tA/\varepsilon} y^\varepsilon(t), \quad \text{i.e.} \quad \partial_t u^\varepsilon(t) = e^{-\frac{t}{\varepsilon}A} f(e^{\frac{t}{\varepsilon}A} u^\varepsilon).$$

Splitting methods e.g. Strang splitting

$$y_{\ell+1} = e^{\frac{h}{2\varepsilon}A} \circ e^{hf} \circ e^{\frac{h}{2\varepsilon}A}(y_\ell)$$

Strang splitting error – Order reduction

$$e^{\frac{h}{2\varepsilon}A} \circ e^{hf} \circ e^{\frac{h}{2\varepsilon}A} = \exp \left(h \left(\frac{1}{\varepsilon}A + f \right) - \frac{h^3}{24\varepsilon^2} [A + 2\varepsilon f, [A, f]] + \dots \right)$$

where $[f, g] = g'f - f'g$ is the Lie bracket of vector fields.

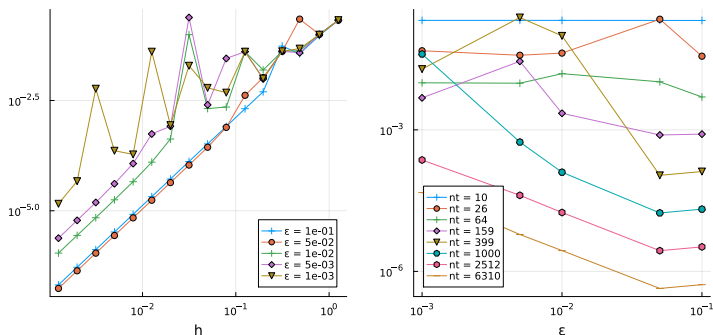
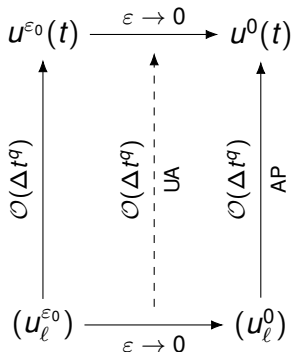


Figure: Error convergence w.r.t. h (left) and ε (right) of the Strang splitting on the Hénon-Heiles model for $t \in [0, 4\pi]$.

Two-scale notions of convergence



Definition – Order of convergence

A method of order q is said to be *uniformly accurate* (UA) if its uniform order of convergence is not degraded, i.e. if

$$\sup_{0 < \epsilon \leq \epsilon_0} \max_{0 \leq \ell \leq N} |u^\epsilon(t_\ell) - u_\ell^\epsilon| = \mathcal{O}(\Delta t^q).$$

We say a method is *asymptotic preserving* (AP) if

$$\lim_{\epsilon \rightarrow 0^+} \max_{0 \leq \ell \leq N} |u^\epsilon(t_\ell) - u_\ell^\epsilon| = \mathcal{O}(\Delta t^q).$$

These notions may depend on the initial conditions (e.g. near-equilibrium).

Order reduction

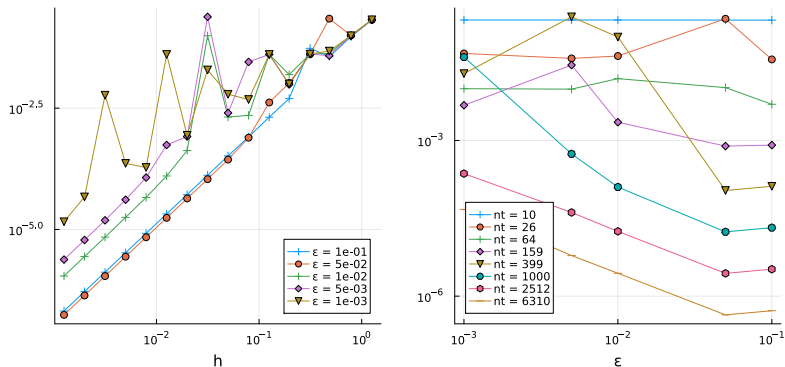


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Uniform accuracy

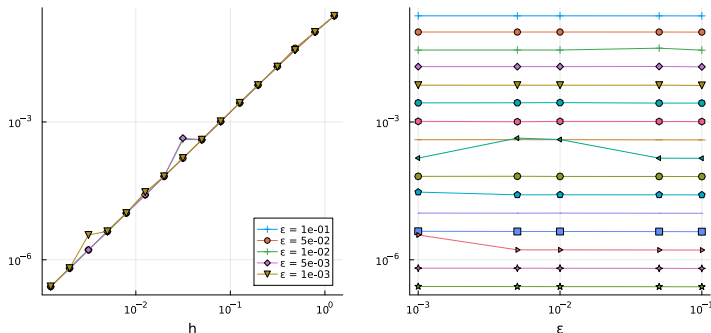


Figure: Error convergence w.r.t. h (left) and ε (right) of the Strang splitting on the first-order averaged Hénon-Heiles model for $t \in [0, 4\pi]$.

Some literature

Different approaches

- high-order averaging (Castella, Chartier, Lemou, Méhats, LT ...)
- asymptotic preserving (AP) schemes (Dimarco, Jin, Pareschi, Toscani, ...)
- exponential integrators (Hochbruck, Lubich, Ostermann, Schratz ...)

Extensions of the averaging approach

- relaxation problems (Castella, Chartier, Lemou, Molmy, LT, ...)
- stochastic case (Laurent, Vilmart)

In some regard, also related to: homogenization, Chapman-Enskog expansion, non-linear geometric optics...

Long-time numerical behaviour

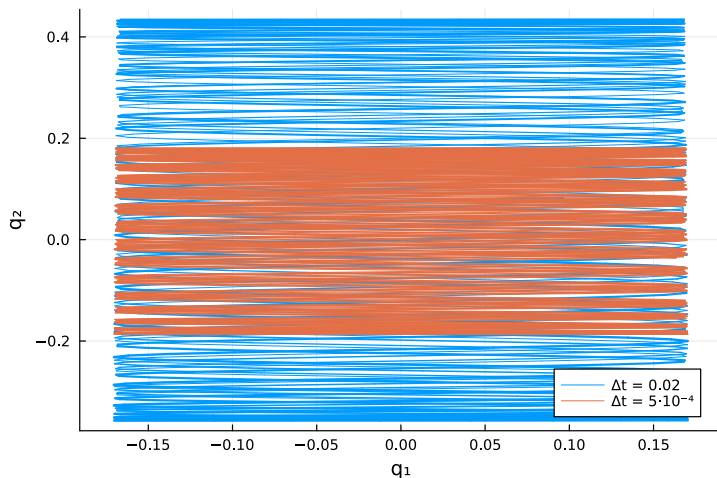


Figure: Trajectory for $t \in [780, 800]$ with $\varepsilon = \pi/100$ for different time steps using the integral RK1 scheme.

The stiff Hénon-Heiles model – Hamiltonian

The system may actually be written in a canonical Hamiltonian form

$$\dot{q} = \nabla_p H(p, q), \quad \dot{p} = -\nabla_q H(p, q)$$

with the Hamiltonian

$$H(q_1, q_2, p_1, p_2) = \underbrace{\frac{1}{2\varepsilon}(p_1^2 + q_1^2)}_{\frac{1}{\varepsilon}H_0} + \underbrace{\frac{1}{2}(p_2^2 + q_2^2) + q_1^2 q_2 - \frac{1}{3}q_2^3}_{H_1}$$

Definition – Hamiltonian structure

A vector field $(\theta, y) \mapsto g(y)$ is said to be *Hamiltonian* if there exists $(\theta, y) \mapsto H(y) \in \mathbb{R}$ such that

$$g(y) = J^{-1} \nabla H(y) \quad \text{where} \quad J^{-1} = \begin{pmatrix} 0 & -I_d \\ I_d & 0 \end{pmatrix}.$$

The midpoint scheme – Energy drift

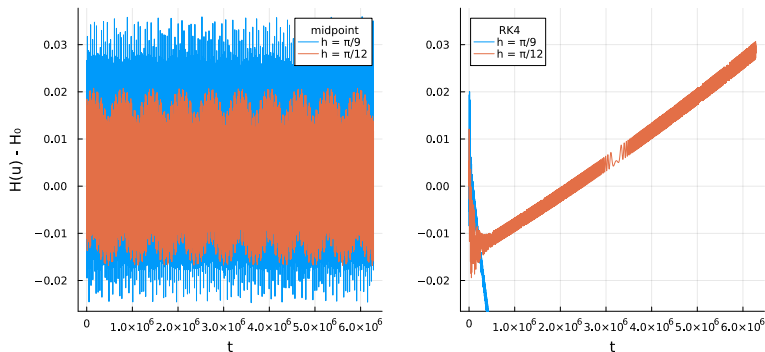


Figure: Energy deviation over time depending on the scheme used to approximate e^{hf} in the Strang splitting.

📺 great visuals in introductory video by braintruffle on YouTube

📖 Hairer, Lubich, Wanner – Geometric Numerical Integration (2006)

Lie group & algebra

In general, it is important to respect the correspondence

$$\text{Lie algebra } \mathfrak{g} \quad \begin{array}{c} \xrightarrow{\text{exp}} \\ \xleftarrow{\text{tangent}} \end{array} \quad \text{Lie group } \mathfrak{G}$$

Examples

- vector fields $\leftrightarrow$ flows
- Hamiltonian $\leftrightarrow$ symplectic
- divergence-free $\leftrightarrow$ volume-preserving



Only some operations preserve structure



e.g. for $g \in \mathfrak{g}$ and $\phi \in \mathfrak{G}$,

$$g \triangleleft \phi := (\partial_u \phi)^{-1} \cdot g \circ \phi \in \mathfrak{g}.$$

$$[f, g] := g'f - f'g \in \mathfrak{g}.$$

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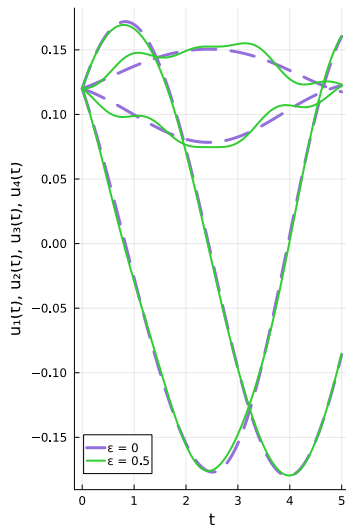
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Filtering out the oscillations



Introduce the “filtered” problem on

$$u^\varepsilon(t) = e^{-tA/\varepsilon} y^\varepsilon(t),$$

and the filtered vector field can be defined as

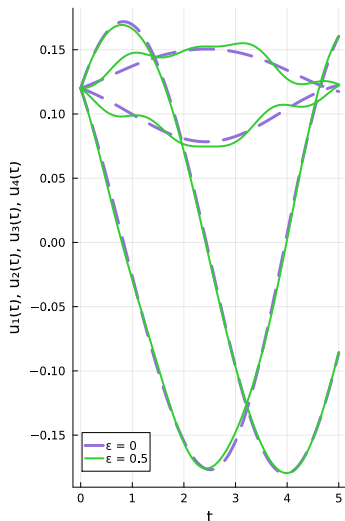
$$f \triangleleft e^{\theta A} = e^{-\theta A} f(e^{\theta A} u) := g_\theta$$

where $(\theta, u) \mapsto g_\theta(u)$ is periodic w.r.t. θ and

$$\partial_t u^\varepsilon(t) = g_{t/\varepsilon}(u^\varepsilon(t)).$$

! $|\partial_t^{k+1} u^\varepsilon(t)| = \mathcal{O}(1/\varepsilon^k)$
therefore the order of numerical schemes is still limited

The averaging ansatz



Limit behaviour

The main dynamics are dictated by the *non-stiff* problem

$$u^\varepsilon(t) = u_0 + \int_0^t \hat{g}_0(u^\varepsilon(s)) ds + \mathcal{O}(\varepsilon),$$

with $\hat{g}_0$ the θ -average vector field.

Averaging

Decompose the solution u^ε as

$$u^\varepsilon(t) = \Phi_{t/\varepsilon}^\varepsilon \circ \exp(tG^\varepsilon) \circ (\Phi_0^\varepsilon)^{-1}(u_0)$$

with $(\theta, u) \mapsto \Phi_\theta^\varepsilon(u) = \text{id} + \mathcal{O}(\varepsilon)$ a periodic change of variable and $u \mapsto G^\varepsilon(u)$ a non-stiff vector field.

The method of Lie series

Homological equation since $u^\varepsilon(t) = \Phi_{t/\varepsilon}^\varepsilon \circ e^{tG^\varepsilon} \circ (\Phi_0^\varepsilon)^{-1}(u_0)$ with $\partial_t u^\varepsilon = g_{t/\varepsilon}(u^\varepsilon)$,

$$\partial_\theta \Phi_\theta^\varepsilon = \varepsilon (g_\theta \circ \Phi_\theta^\varepsilon - D\Phi_\theta^\varepsilon \cdot G^\varepsilon)$$

➡ refine Φ^ε with a fixed point ⚠ but there is no structure here!

Lie series Construct generators $\varepsilon a^{[k]} = \mathcal{O}(\varepsilon^k)$ such that

$$\Phi_\theta^{[n]} = \exp\left(\varepsilon a_\theta^{[n]}\right) \circ \dots \circ \exp\left(\varepsilon a_\theta^{[1]}\right),$$

with $\Phi^{[0]} = \text{id}$, closure $\widehat{a}_0^{[k]} = 0$ and the iterations

$$\partial_\theta a_\theta^{[n+1]} = (D\Phi_\theta^{[n]})^{-1} \left(g_\theta \circ \Phi_\theta^{[n]} - \frac{1}{\varepsilon} \partial_\theta \Phi_\theta^{[n]} \right) - G^{[n+1]} = \mathcal{O}(\varepsilon^n),$$

👍 every element is in the Lie algebra

Averaging as a higher-order filtering

$$y^\varepsilon(t) \xleftarrow{e^{\theta A}} u^\varepsilon(t) \xleftarrow{\exp(\varepsilon a_\theta^{[1]})} v^{[1]}(t) \xleftarrow{\exp(\varepsilon a_\theta^{[2]})} \dots$$

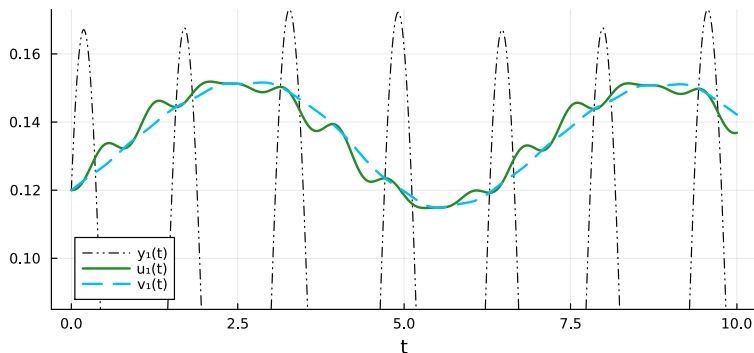


Figure: Original, filtered and first-order pulled-back solutions for $\varepsilon = 0.25$.

The pullback approach

Knowing the change of variable $\Phi^{[n]}$, we define

$$v^{[n]}(t) = (\Phi_{t/\varepsilon}^{[n]})^{-1}(u^\varepsilon(t)),$$

which satisfies the new differential equation

$$\begin{aligned}\partial_t v^{[n]}(t) &= (D\Phi_{t/\varepsilon}^{[n]})^{-1} \left(g_{t/\varepsilon} \circ \Phi^{[n]} - \frac{1}{\varepsilon} \partial_\theta \Phi^{[n]} \right) \\ &= G^{[n+1]}(v^{[n]}(t)) + \partial_\theta a_{t/\varepsilon}^{[n+1]}(v^{[n]}(t)) \\ &=: g_{t/\varepsilon}^{[n]}(v^{[n]}(t))\end{aligned}$$

👍 the oscillations are now small

Because $a^{[n+1]} = \mathcal{O}(\varepsilon^n)$, the new vector field satisfies (formally)

$$|\partial_t^{k+1} v(t)| = \mathcal{O}(1/\varepsilon^{\min(0, k-n)}).$$

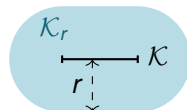
Assumptions – Analyticity and complex expansions

Assumptions

- The operator A generates a known 2π -periodic group $\theta \mapsto e^{\theta A}$
- For all ε small enough, the solution stays in some $\mathcal{K}$ for $t \in [0, 1]$

Introduce the complex extensions of $\mathcal{K}$ as

$$\mathcal{K}_r := \{u + \tilde{u}, \quad (u, \tilde{u}) \in \mathcal{K} \times X_{\mathbb{C}}, |\tilde{u}|_{\mathbb{C}} \leq r\}.$$



Assumption – Analyticity

There exists some $R > 0$ such that the vector field $(\theta, u) \mapsto g_{\theta}(u)$ is of class C^{μ} w.r.t. θ and u -analytic in $\mathcal{K}$, of radius everywhere greater than $2R$. Furthermore,

$$\sup_{(\theta, u) \in \mathbb{T} \times \mathcal{K}_{2R}} |g_{\theta}(u)| =: \|g\|_{2R} \leq M.$$

Well-posedness of averaging

The homological equation is “solved” iteratively with the relation

$$\partial_{\theta} a_{\theta}^{[n+1]} = g^{[n]} - \widehat{g}_0^{[n]}, \quad \text{and} \quad \Phi^{[0]} = \text{id},$$

with $g^{[n]} = (D\Phi^{[n]})^{-1} (g_{\theta} \circ \Phi^{[n]} - \frac{1}{\varepsilon} \partial_{\theta} \Phi^{[n]})$.

Well-posedness and accuracy of the averaging procedure

There exists $\varepsilon_0 > 0$ such that for all $n \in \mathbb{N}$, the averaging procedure is well defined for $0 < \varepsilon \leq \varepsilon_n := \frac{\varepsilon_0}{n+1}$. Specifically,

$$\|\Phi^{[n]} - \text{id}\| \lesssim \frac{\varepsilon}{\varepsilon_n}, \quad \|g^{[n]}\| \lesssim 1, \quad \|g^{[n]} - \widehat{g}_0^{[n]}\| \lesssim \left(\frac{\varepsilon}{\varepsilon_n}\right)^n.$$

Their derivatives w.r.t. θ are of the same size, i.e. respectively $\mathcal{O}(\varepsilon)$, $\mathcal{O}(1)$ and $\mathcal{O}(\varepsilon^n)$ up to order μ .

Well-posedness of the pullback problem

When differentiating the new problem

$$\partial_t v^{[n]}(t) = G^{[n+1]}(v^{[n]}(t)) + \partial_\theta a_{t/\varepsilon}^{[n+1]}(v^{[n]}(t))$$

the oscillations get divided by ε , but are small enough to not generate stiffness!

Theorem – Uniform accuracy (Chartier, Lemou, Méhats, Vilmart 2021)

This problem is non-stiff up to its $(n + 1)$ -th derivative and can therefore be solved with uniform accuracy up to order n for standard schemes and order $n + 1$ with integral schemes. In other words, we may obtain

$$|v(t_\ell) - v_\ell| \leq C\Delta t^{n+1}$$

with C independent of ε .

Multi-frequency homological equation

Multiple frequencies $(\omega_1, \dots, \omega_s)$ such that there is a decomposition

$$e^{\tau A} = \sum_{\alpha \in \mathbb{Z}^s} e^{i\alpha \cdot \omega} \hat{P}_\alpha$$

then identify the **multi-phase** vector field

$$(\theta, u) \in \mathbb{T}^s \times \mathcal{K} \mapsto g_\theta(u) \quad \text{s.t.} \quad g_{\omega\tau} = f \triangleleft e^{\tau A}.$$

Homological equation The iterations are now

$$\sum_i \omega_i \frac{\partial}{\partial \theta_i} a_\theta^{[n+1]} = g_\theta^{[n]} - \hat{g}_0^{[n]}$$

which is integrated in Fourier space for $\alpha \in \mathbb{Z}^s$, $\alpha \neq 0$,

$$\hat{a}_\alpha^{[n+1]} = \frac{1}{i(\alpha \cdot \omega)} \hat{g}_\alpha^{[n]} \quad \text{! small divisors!}$$

Multi-frequency homological equation

Assumption - Strong non-resonance

The frequencies are strongly non-resonant: there exist $c_D, \nu > 0$ such that for all $\alpha \in \mathbb{Z}^s \setminus \{0\}$

$$|\alpha \cdot \omega| \geq c_D |\alpha|^{-\nu}.$$

➔ Quantifies the small divisors: if g is H_θ^μ , then $g^{[n]}$ is $H_\theta^{\mu-n\nu}$.

Corollary – Well-posedness under strong non-resonance

If $(\theta, u) \mapsto g_\theta(u)$ is analytic w.r.t. θ with radius 2μ , then the previous results hold for

$$0 < \varepsilon \leq \varepsilon_n := \frac{\varepsilon_0}{(n+1)^{1+\nu}}.$$

Additionally, the maps are analytic with radius μ .

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Using the midpoint rule

Compute the flow in a structure-preserving manner,

$$\exp\left(\varepsilon \mathbf{a}_\theta^{[n]}\right) \approx \phi_\theta^{[n]} := \text{id} + \varepsilon \mathbf{a}_\theta^{[n]} \left(\frac{1}{2} (\text{id} + \phi_\theta^{[n]}) \right)$$

❓ Will this impact uniform accuracy?

➡ Only for $n \geq \varepsilon^3$ because $\phi^{[n]} = \exp(\varepsilon \mathbf{a}^{[n]}) + \mathcal{O}(\varepsilon)^3$

Derivatives

$$\begin{aligned} \frac{1}{\varepsilon} \partial_\theta \phi_\theta^{[n]} &= \partial_\theta \mathbf{a}_\theta^{[n]} \left(\frac{1}{2} (\text{id} + \phi_\theta^{[n]}) \right) + \frac{1}{2} \varepsilon D \mathbf{a}_\theta^{[n]} \left(\frac{1}{2} (\text{id} + \phi_\theta^{[n]}) \right) \cdot \frac{1}{\varepsilon} \partial_\theta \phi_\theta^{[n]} \\ &= (g_\theta^{[n-1]} - \langle g^{[n-1]} \rangle) \left(\frac{1}{2} (\text{id} + \phi_\theta^{[n]}) \right) \\ &\quad + \frac{1}{2} \varepsilon D \mathbf{a}_\theta^{[n]} \left(\frac{1}{2} (\text{id} + \phi_\theta^{[n]}) \right) \cdot \frac{1}{\varepsilon} \partial_\theta \phi_\theta^{[n]} \end{aligned}$$

➡ fixed-point for $\frac{1}{\varepsilon} \partial_\theta \phi_\theta^{[n]}$, computing the jacobian-vector product (jvp) with automatic differentiation

Validation on the Hénon-Heiles model

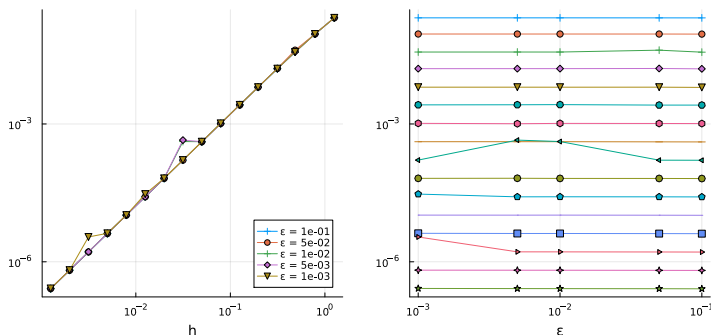


Figure: Error convergence w.r.t. h (left) and ϵ (right) of the Strang splitting on the first-order averaged Hénon-Heiles model for $t \in [0, 4\pi]$.

Summary

Starting from an ansatz

$$u^\varepsilon(t) = \Phi_{t/\varepsilon}^\varepsilon \circ \exp(tG^\varepsilon) \circ (\Phi_0^{[n]})^{-1}(u_0)$$

with Φ^ε periodic and G^ε non-stiff, we derived

- a systematic high-order averaging procedure
- a framework which extends fairly naturally to other contexts
- *modified problems* solvable with uniform accuracy
- and which naturally preserve some geometric properties

However, some obvious limitations remain:

- the computational cost increases exponentially with the order n
- this may not be suited for low-regularity problems

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